



# Another Automatic Kernel Generator on Huawei NPU with Polyhedral Compilation

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# Outline

- Polyhedral Compilation
- Front End
- Back End
- Recursive Approach for Schedule Generation
- Auto-tuning
- Auto-fusion
- Future Work



# Polyhedral Compilation

- Integer Set Library (ISL)

A[i, j] :  $0 \leq i < 16$  and  $0 \leq j < 256$

B[i, j] :  $0 \leq i < 16$  and  $0 \leq j < 256$

Input

C[i] :  $0 \leq i < 16$

Output

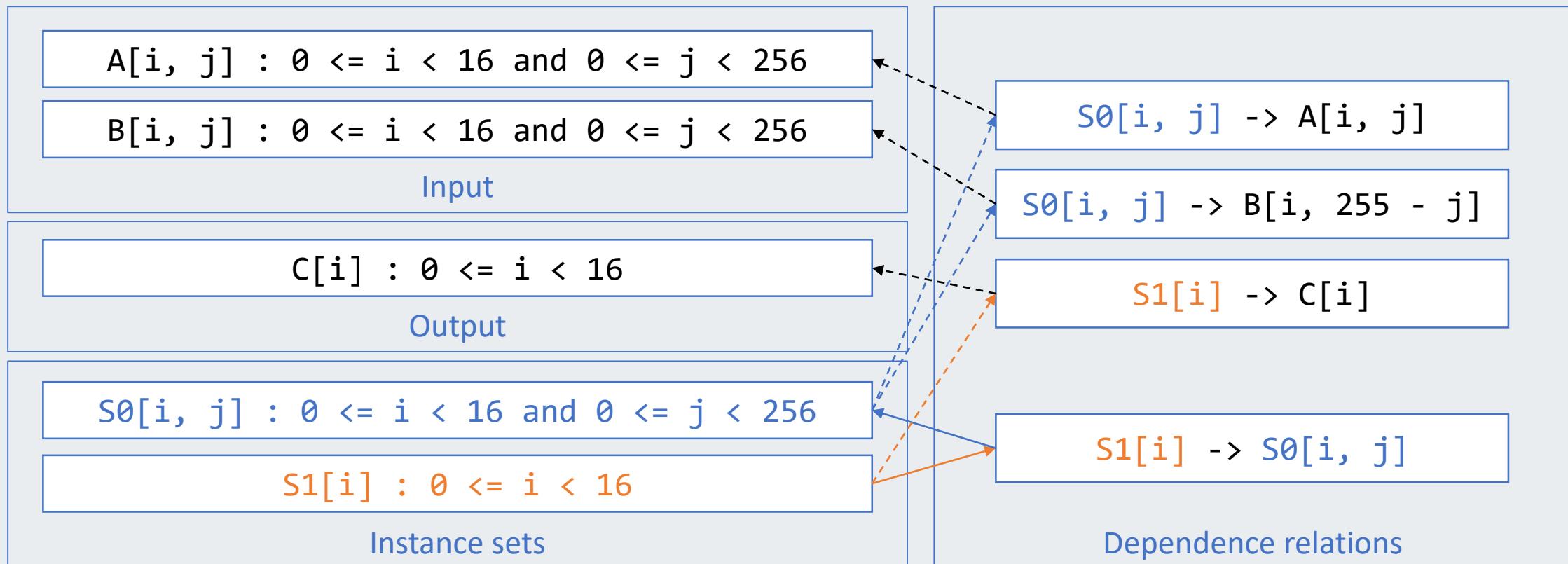
S0[i, j] :  $0 \leq i < 16$  and  $0 \leq j < 256$

S1[i] :  $0 \leq i < 16$

Instance sets

# Polyhedral Compilation

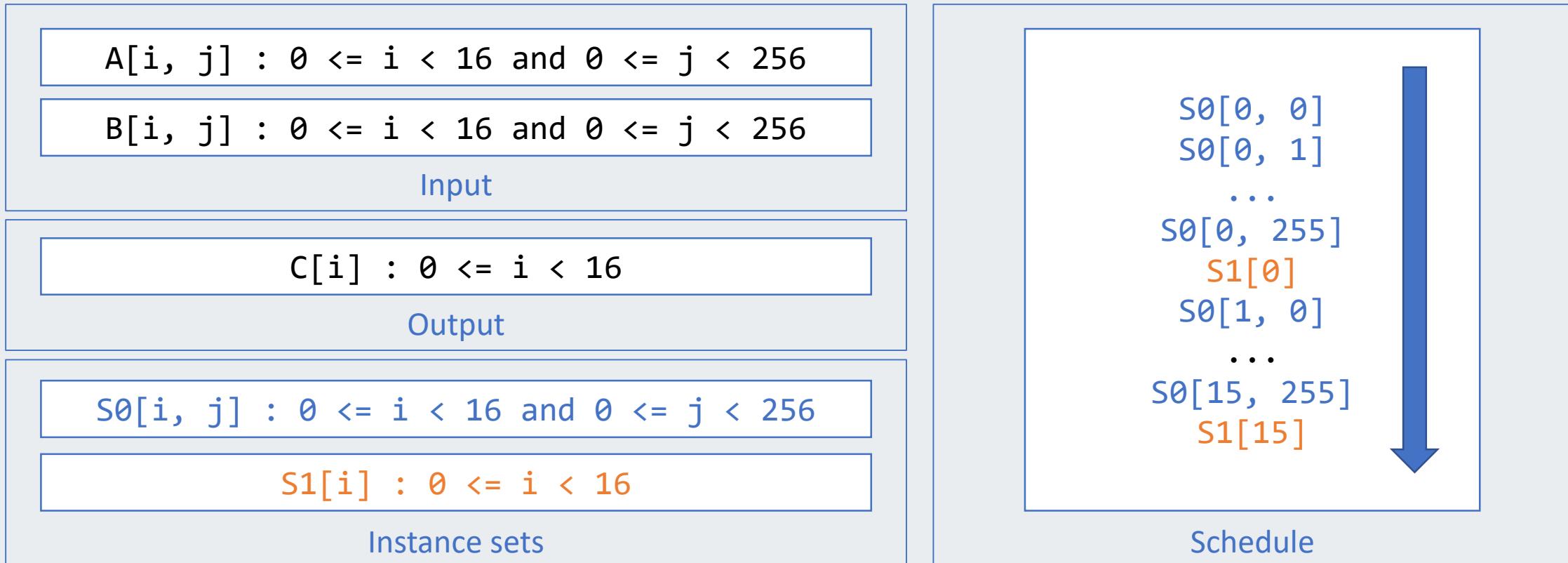
- Integer Set Library (ISL)



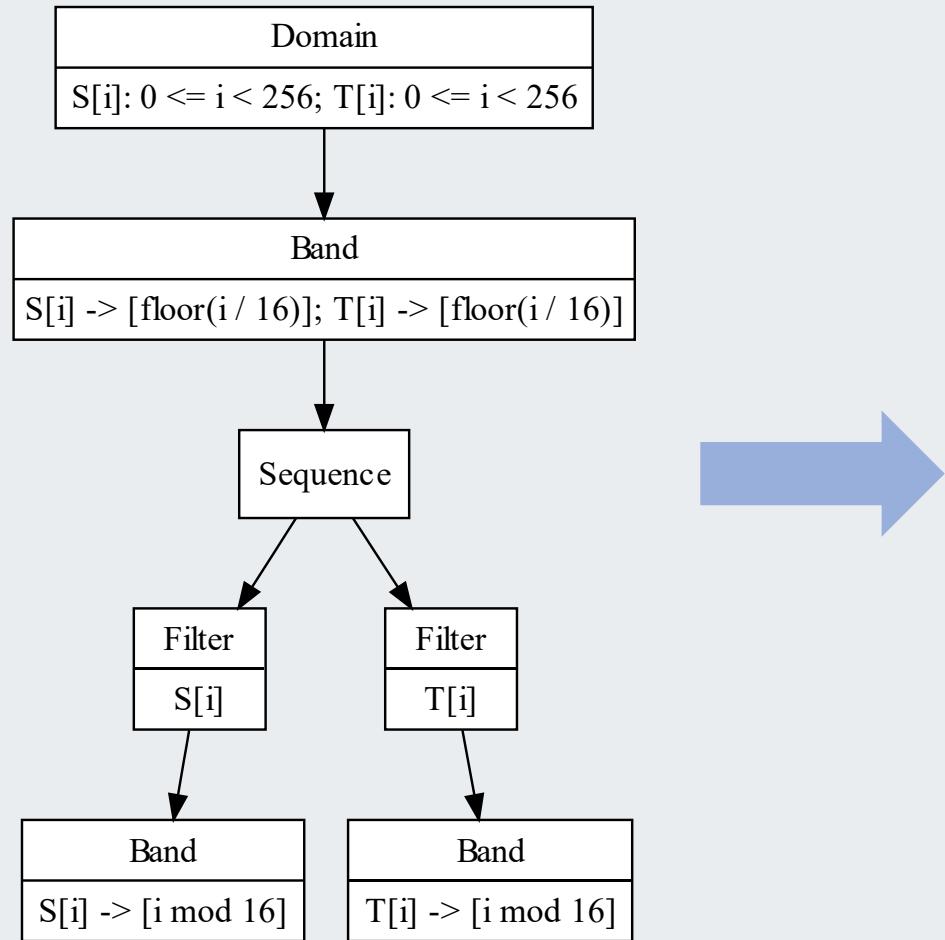


# Polyhedral Compilation

- Integer Set Library (ISL)



# Schedule Trees




```

● ● ●

for (c0 = 0; c0 < 16; c0 += 1) {
    for (c1 = 0; c1 < 16; c1 += 1) {
        S(c0 * 16 + c1);
    }
    for (c2 = 0; c2 < 16; c2 += 1) {
        T(c0 * 16 + c2);
    }
}
  
```

The code generated from the schedule tree shows nested loops for  $c0$ ,  $c1$ , and  $c2$ , each ranging from 0 to 15. The innermost loop for  $c1$  and  $c2$  is associated with the  $S$  assignment, while the outermost loop for  $c0$  is associated with the  $T$  assignment.



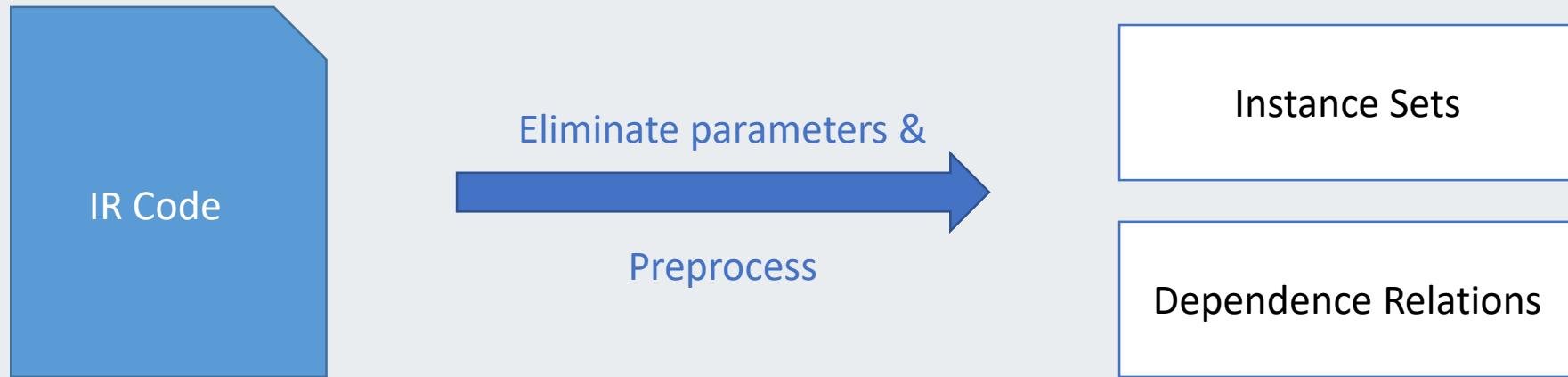
# Front End – IR Code



```
opdef Conv2D<
    N: int, C0: int, C1: int, H: int, W: int, OutC0: int, OutC1: int,
    Kernel: int, Stride: int, Group: int
>(
    data[N, C0, H, W, C1],
    weight[OutC0, floordiv(C0, Group), Kernel, Kernel, C1, OutC1]
) -> (
    res[N, OutC0, add(floordiv(sub(H, Kernel), Stride), 1),
        add(floordiv(sub(W, Kernel), Stride), 1), OutC1]
) {
    mult[n, u, h, w, x, i, j, y, v] = mul(
        data[n, x, add(h, i), add(w, j), y],
        weight[u, sub(x, mul(floordiv(x, floordiv(C0, Group)), floordiv(C0, Group))), i, j, y, v]
    )
    res[n, u, h, w, v] = reduce<add, 0.0>|{
        mult[n_, u_, h_, w_, x, i, j, y, v_]: and(
            eq(n, n_), eq(u, u_), eq(v, v_), eq(mul(h, Stride), h_), eq(mul(w, Stride), w_),
            le(0, i), lt(i, Kernel), le(0, j), lt(j, Kernel), le(0, x), lt(x, C0), le(0, y), lt(y, C1)
        )
    }
}
```



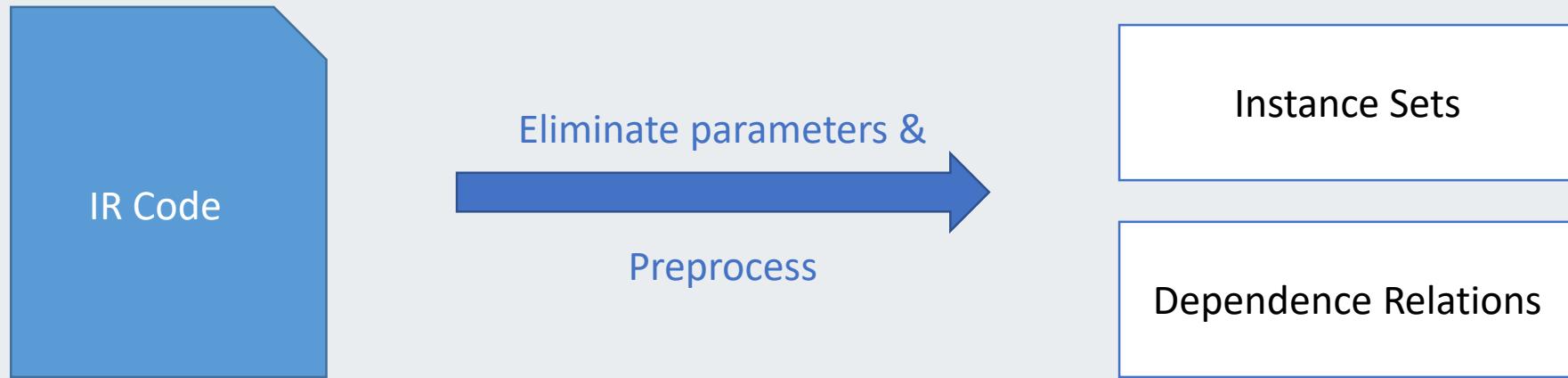
# Front End – the Polyhedral Model



```
opdef Dot<N: int, M: int>(A[N, M], B[N, M]) -> (C[N]) {  
    T[i, j] = mul(A[i, j], B[i, j])  
    C[i] = reduce<add, 0.0>({  
        T[u, v]: and(eq(u, i), le(0, v), lt(v, M))  
    })  
}
```



# Front End – the Polyhedral Model



```
opdef Dot<>(A[16, 256], B[16, 256]) -> (C[16]) {
    T[i, j] = mul(A[i, j], B[i, j])
    C[i] = reduce<add, 0.0>({
        T[u, v]: and(eq(u, i), le(0, v), lt(v, 256))
    })
}
```



# Front End – the Polyhedral Model

IR Code

Eliminate parameters &



Instance Sets

Dependence Relations

$T[i, j] : 0 \leq i < 16 \text{ and } 0 \leq j < 256$

$C[i] : 0 \leq i < 16$

Instance sets

$C[i] \rightarrow _C g_m[i]$

...

$C[i] \rightarrow T[i, j]$

Dependence relations



# Front End – Fusion



```
opdef Dot<>(A[16, 256], B[16, 256]) -> (C[16]) {
    T[i, j] = mul(A[i, j], B[i, j])
    C[i] = reduce<add, 0.0>|{
        T[u, v]: and(eq(u, i), le(0, v), lt(v, 256))
    }
}
```

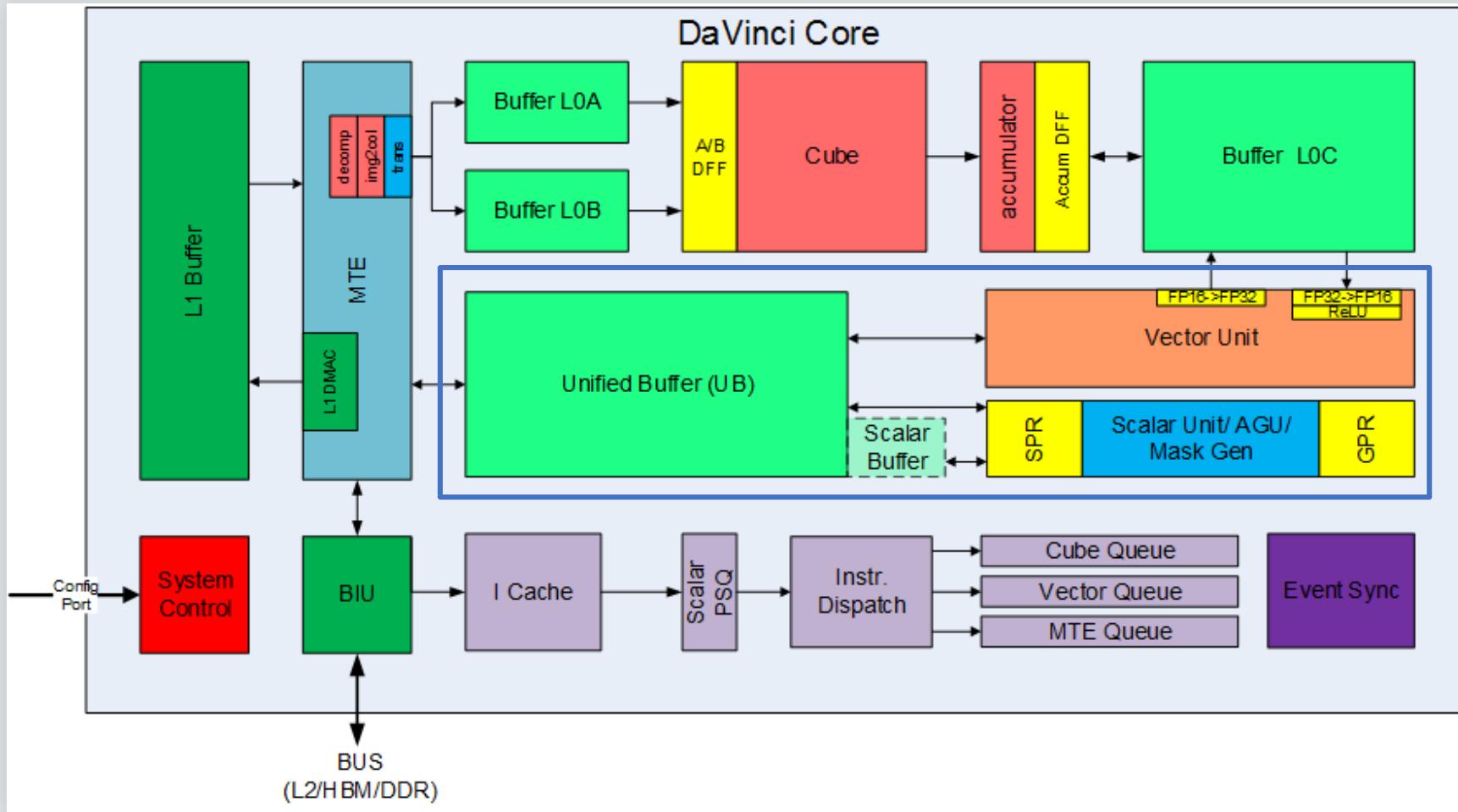


```
opdef ReLU<>(A[16]) -> (B[16]) {
    B[i] = relu(A[i])
}
```



```
opdef Dot_ReLU<>(A_0[16, 256], B_0[16, 256]) -> (B_1[16]) {
    T_0[i, j] = mul(A_0[i, j], B_0[i, j])
    C_0[i] = reduce<add, 0.0>|{
        T_0[u, v]: and(eq(u, i), le(0, v), lt(v, 256))
    }
    B_1[i] = relu(C_0[i])
}
```

# Da Vinci Architecture



Da Vinci Architecture on Huawei Ascend 310 NPU



# Back End: TIK

- TIK: a wrapper of the TVM IR builder
- Low-level interfaces:
  - Tensor management, control flows, emitting instructions, ...

```
from tbe import tik
tik_instance = tik.Tik()
data_A = tik_instance.Tensor('float16', (128,), name='data_A', scope=tik.scope_gm)
data_B = tik_instance.Tensor('float16', (128,), name='data_B', scope=tik.scope_gm)
data_C = tik_instance.Tensor('float16', (128,), name='data_C', scope=tik.scope_gm)
data_A_ub = tik_instance.Tensor('float16', (128,), name='data_A_ub', scope=tik.scope_ubuf)
data_B_ub = tik_instance.Tensor('float16', (128,), name='data_B_ub', scope=tik.scope_ubuf)
data_C_ub = tik_instance.Tensor('float16', (128,), name='data_C_ub', scope=tik.scope_ubuf)
tik_instance.data_move(data_A_ub, data_A, 0, 1, 128 //16, 0, 0)
tik_instance.data_move(data_B_ub, data_B, 0, 1, 128 //16, 0, 0)
tik_instance.vec_add(128, data_C_ub[0], data_A_ub[0], data_B_ub[0], 1, 8, 8, 8)
tik_instance.data_move(data_C, data_C_ub, 0, 1, 128 //16, 0, 0)
tik_instance.BuildCCE(kernel_name='simple_add', inputs=[data_A, data_B], outputs=[data_C])
```



# Recursive Approach for Schedule Generation

## Input

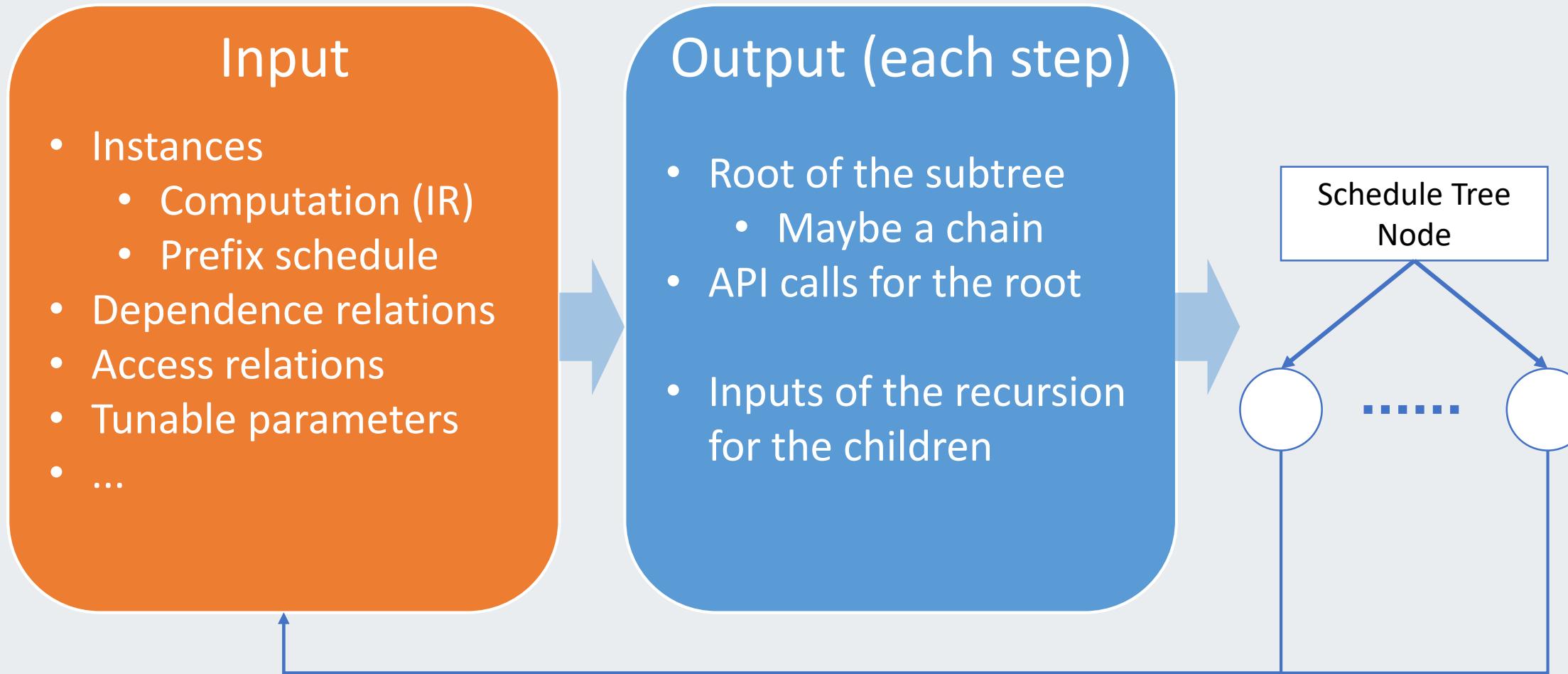
- Instances
  - Computation (IR)
  - Prefix schedule
- Dependence relations
- Access relations
- Tunable parameters
- ...

?

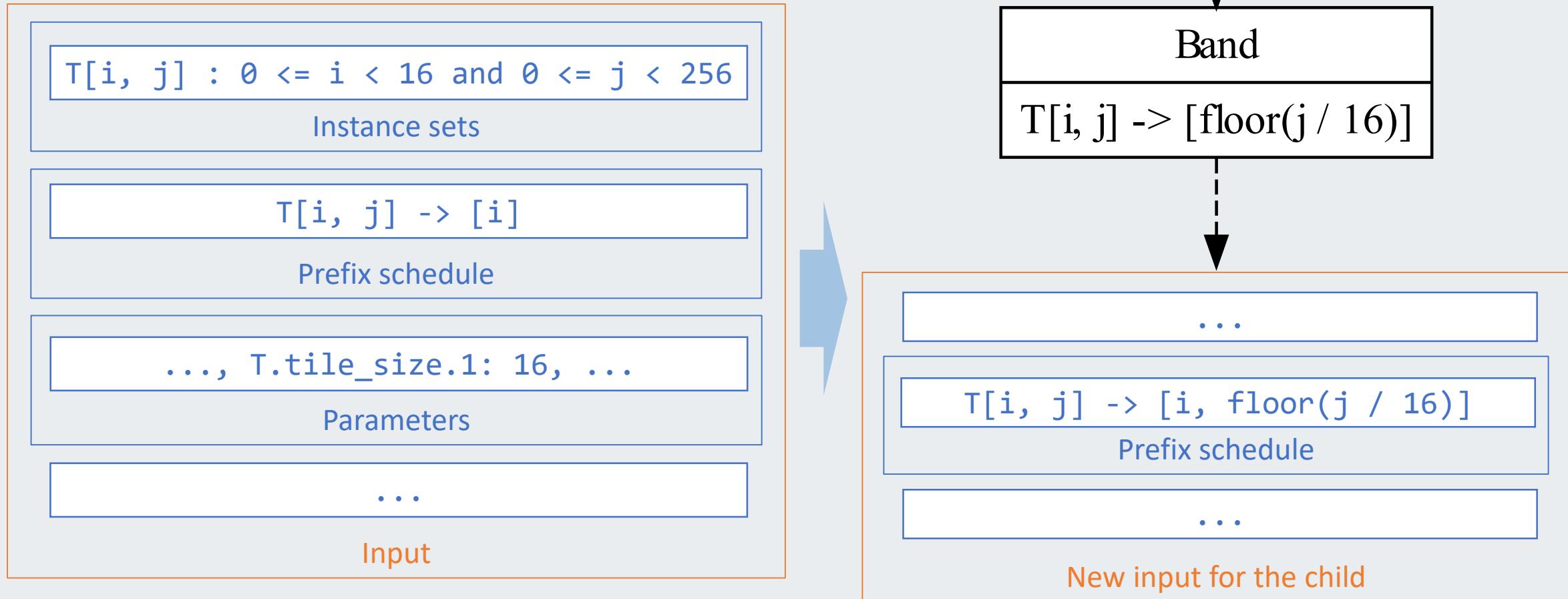
## Output

- Schedule tree (subtree)
- TIK API arguments and calls

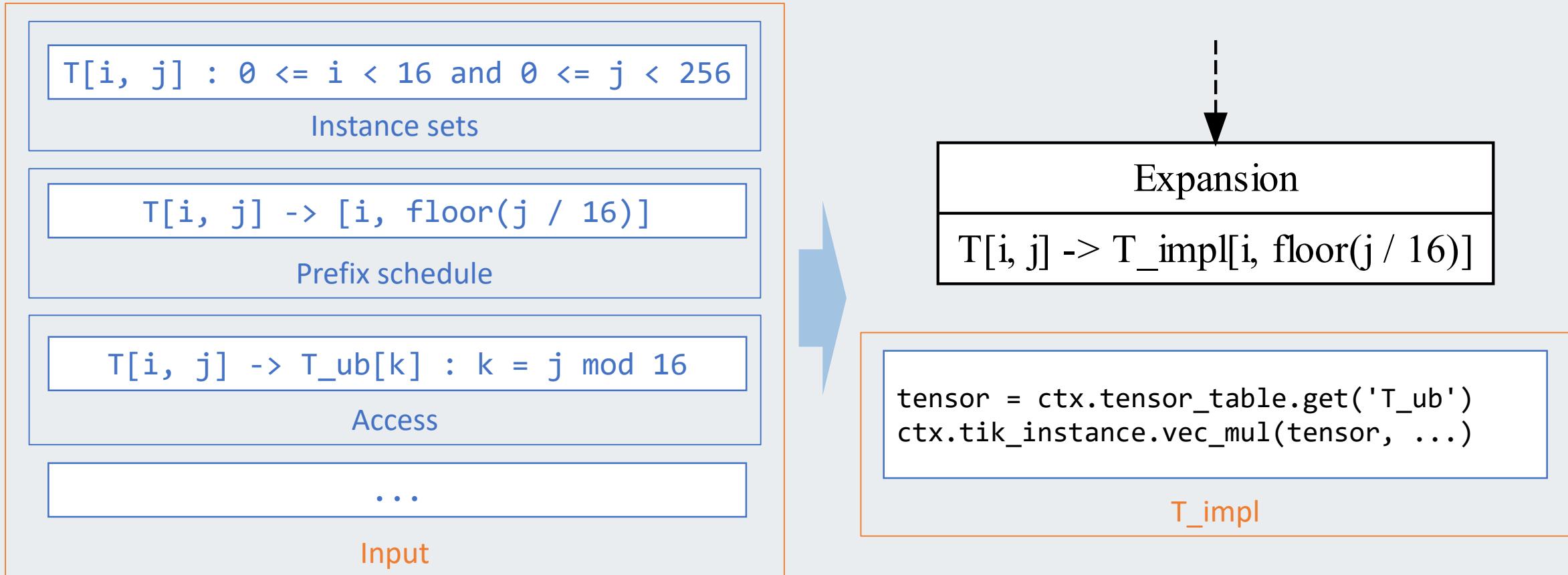
# Recursive Approach for Schedule Generation



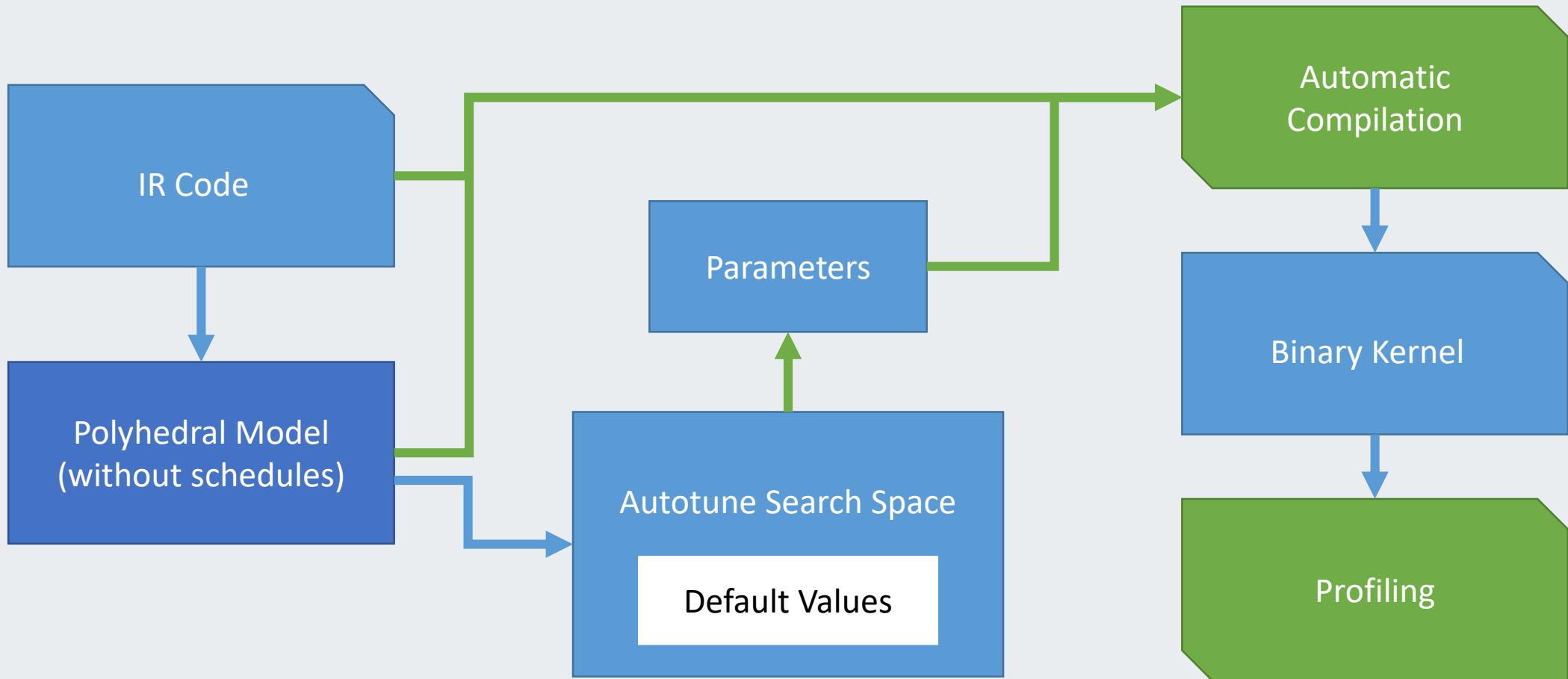
# Loop Tiling



# Vectorization



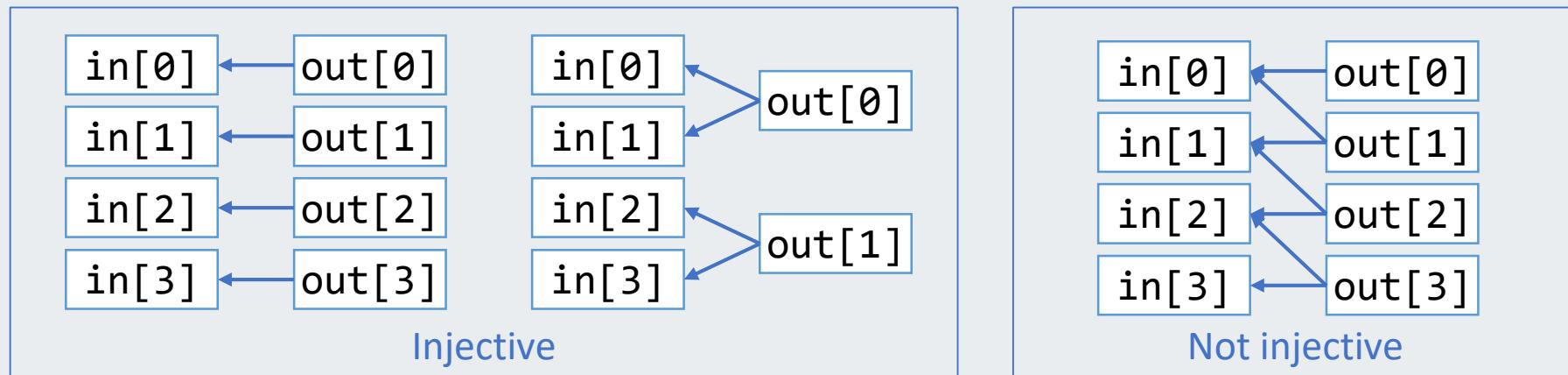
# Auto-tuning



# Auto-fusion



- Dependence relations of outputs on inputs
  - Injective → “fusable” (in most cases)
  - Typically, elementwise operators will be detected as fusible kernels





# Future Work

- Utilize “cube” instructions and other hardware accelerations
- Computations → low-level structures and statements
  - Complex
  - Lots of unnecessary details in the implementation
  - Solution: More levels of IR? More stages?
- Recursive compilation? Beam Search!
  - Redesign of auto-tuning
- ...



# Acknowledgments





# Thank you for listening

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